From CCS to CSP: the m-among-n Synchronisation Approach

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We present an alternative translation from CCS to an extension of CSP based on m-among-n synchronisation (called CSPmn). This translation is correct up to strong bisimulation. Unlike the g-star renaming approach ([4]), this translation is not limited by replication (viz., recursion with no nested parallel composition). We show that m-among-n synchronisation can be implemented in CSP based on multiway synchronisation and renaming.

1 Introduction

In [4], the authors present a translation from CCS [1] into CSP [22, 20], ccs2csp, which is correct up to strong bisimulation (cf. [10]). This means that a CCS process is strong bisimilar to its CSP translation. ccs2csp has been implemented in Haskell (cf. [23]), which allows using the model-checker FDR [7] for analysing translated CCS terms. In the course of the same work, the authors have proposed an alternative translation, ccs2cspg, correct up to failure equivalence. Both translations differ in the translation of the prefix term $\tau.P$, translated into $(\text{tau} \rightarrow \text{ccs2csp}(P)) \setminus \text{tau}$ in the first case, and ccs2cspg$(P)$ in the second case.

In this paper we present yet a third alternative, ccs2csp3, achieved by first extending CSP with m-among-n synchronisation [9], from which we can derive multiway (or n-among-n) synchronisation, the default CSP synchronisation mechanism, and binary synchronisation (used in CCS). Then, we translate CCS parallel composition into the binary version of CSP parallel operator. The resulting translation is correct up to strong bisimulation.

The translations in [4] were achieved by hard coding binary synchronisation into CCS before going to CSP. Using a renaming function, $g^*$, the translations generated unique pairs of indices between any two pairs of complementary prefixes in a parallel composition, e.g., $(a, \bar{a}) \mapsto \{(a_{12}, \bar{a}_{12}), (a_{13}, \bar{a}_{13})\}$. This effectively made synchronising prefix pairs unique. Although these indices were generated in CCS, the $g^*$-renaming approach shows how to enforce binary synchronisation even in CSP: given a CSP process $P \parallel Q \parallel R$, to ensure binary synchronisations on $a$, assign unique indices to $a$ accordingly, through renaming. E.g., $P[a_{12}, a_{13}] / a \parallel Q[a_{12} / a] \parallel R[a_{13} / a]$ ensures that pairs of processes $(P, Q)$ and $(P, R)$ can synchronise respectively, but not $(Q, R)$. This approach, which we call the Gstar approach, has been encoded in the translation tool and the resulting CSP terms can be analysed in FDR immediately.

m-among-n synchronisation [9] demands adding new rules to CSP, hence it would require updating FDR first. In other words, the CSP terms resulting from our new translation, ccs2csp3, cannot immediately be analysed in FDR. Nonetheless, function $g^*$ implements binary synchronisation, hence, can be taken for an implementation of 2-among-n synchronisation.

The Gstar approach does not allow translating recursive terms with nested parallelism (or replication). That is because function $g^*$ needs to generate every synchronisation index so the translation can
terminate. With \(m\)-among-\(n\) synchronisation, we need only one index to separate interleaving from synchronisation, i.e., we map every CCS name unto two CSP events, e.g., \(a \mapsto \{a, a_s\}\), where \(a_s\) is the synchronisation event. Therefore, this new translation is not limited by parallel under recursion.

Our main contribution in this paper hence is a new translation from CCS into CSP which is correct up to strong bisimulation, is not limited by parallel under recursion, but cannot be immediately analysed with FDR. As a byproduct, we define \(m\)-among-\(n\) synchronisation for CSP processes. We call the corresponding extension CSP\(_{mn}\). We show that CSP\(_{mn}\) preserves CSP axioms by defining \(m\)-among-\(n\) synchronisation in terms of both multiway synchronisation and renaming. The translation from CSP\(_{mn}\) into CSP is limited by parallel under recursion as it requires generating unique indices for all possible combinations of synchronising processes.

## 2 Correct Translation, CCS(Tau), CSP, CCS-to-CSP

### 2.1 Correct Translations

A correct translation of one language into another is a mapping from the valid expressions in the first language to those in the second, that preserves their meaning (for some definition of meaning). Below we recall the two main definitions of correctness from [10].

Let \(L = (T_L, \llbracket \cdot \rrbracket_L)\) denote a language as a pair of a set \(T_L\) of valid expressions in \(L\) and a surjective mapping \(\llbracket \cdot \rrbracket_L : T_L \rightarrow D_L\) from \(T_L\) to some set of meanings \(D_L\). Candidate instances of \(\llbracket \cdot \rrbracket_L\) are traces and failures (cf. [14, 21]).

**Definition 1** (Correct Translation up to Semantic Equivalence [10]). A translation \(T : T_L \rightarrow T_{L'}\) is correct up to a semantic equivalence \(\approx\) on \(D_L \cup D_{L'}\) when \(\llbracket E \rrbracket_L \approx \llbracket T(E) \rrbracket_{L'}\) for all \(E \in T_L\).

Operational correspondence allows matching the transitions of two processes, which can help determine the appropriate relation (semantic equivalence) between a term and its translation. Let the operational semantics of \(L\) be defined by the labelled transition system \((T_L, \text{Act}_L, \rightarrow_L)\), where \(\text{Act}_L\) is the set of labels and \(E \xrightarrow{\lambda} E'\) defines transitions with \(E, E' \in T_L\) and \(\lambda \in \text{Act}_L\).

**Definition 2** (Labelled Operational Correspondence, [8, 19]). Let \(T : T_L \rightarrow T_{L'}\) be a mapping from the expressions of a language \(L\) to those of a language \(L'\), and let \(f : \text{Act}_L \rightarrow \text{Act}_{L'}\) be a mapping from the labels of \(L\) to those of \(L'\). A translation \(\langle T, f \rangle\) is operationally corresponding w.r.t. a semantic equivalence \(\approx\) on \(D_L \cup D_{L'}\) if it is:

- **Sound**: \(\forall E, E' : E \xrightarrow{\lambda} E'\) imply that \(\exists F : T(E) \xrightarrow{f(\lambda)} L' F\) and \(F \approx T(E')\)
- **Complete**: \(\forall E, F : T(E) \xrightarrow{\lambda} L' F\) imply that \(\exists E' : E \xrightarrow{\lambda'} E'\) and \(F \approx T(E') \land \lambda' = f(\lambda)\)

The previous two definitions coincide when the semantic equivalence \(\approx\) is strong bisimulation (Def[3]) and \(f\) is the identity.

### 2.2 CCS, CCSTau

**CCS**. CCS (Calculus of Communicating Systems) [17, 11] is a process algebra that allows reasoning about concurrent systems. CCS represents programs as processes, whose behaviour is determined by
Table 1: SOS rules for CCS

<table>
<thead>
<tr>
<th>Rule</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Prefix</td>
<td>( \alpha.P \xrightarrow{\alpha} P )</td>
</tr>
<tr>
<td>Sum</td>
<td>( P \xrightarrow{\alpha} P' )</td>
</tr>
<tr>
<td>Com</td>
<td>( P \xrightarrow{\alpha} P', Q \xrightarrow{\alpha} Q' ) ( P\parallel Q \xrightarrow{\alpha} P'\parallel Q' )</td>
</tr>
<tr>
<td>Res</td>
<td>( P \xrightarrow{\alpha}, P' \alpha \notin B ) ( P \parallel B \xrightarrow{\alpha} P' \parallel B )</td>
</tr>
<tr>
<td>Par</td>
<td>( P \xrightarrow{\alpha}, P' )</td>
</tr>
<tr>
<td>Rec</td>
<td>( P[\mu X.P/X] \xrightarrow{\alpha} P' )</td>
</tr>
</tbody>
</table>

rules specifying their possible execution steps. The syntax of CCS processes is defined by the following BNF:

\[
CCS ::= 0 | \alpha.P | P + Q | P \parallel Q | P \mid B | \mu X.P
\]

Let \( \mathcal{N} \) denote an infinite set of names; let \( a, b, c, \ldots \) range over \( \mathcal{N} \). Let \( \overline{\mathcal{N}} = \{ \overline{a} | a \in \mathcal{N} \} \) denote the set of conames. Let \( \overline{L} = \mathcal{N} \cup \overline{\mathcal{N}} \) denote the set of all possible labels. The set of labels of a process \( P \) is denoted by \( \overline{L}(P) \) (\cite{17} Def.2, p52). Let \( \tau \) denote the silent or invisible action. Let \( Act = \mathcal{N} \cup \overline{\mathcal{N}} \cup \{ \tau \} \) denote the set of all possible actions that a process can perform. Let \( \alpha, \beta, \ldots \) range over \( Act \). The SOS semantics of CCS are given in Table 1.

Informally: 0 (or \( \text{NIL} \)) is the process that performs no action. \( \alpha.P \) is the process that performs an action \( \alpha \) and then behaves like \( P \). \( P + Q \) is the process that behaves either like \( P \) or like \( Q \). \( P \parallel Q \) is the process that executes \( P \) and \( Q \) in parallel: if both \( P \) and \( Q \) can engage in an action \( a \) then, their execution corresponds to interleaving, e.g., \( a.0|a.0 \equiv a.a.0 \); if \( P \) can engage in action \( a \), \( Q \) in the complementary action \( \bar{a} \), then, either \( P \) and \( Q \) interleave on \( a \) or they synchronise and the result of synchronisation is the invisible action \( \tau \), e.g., \( a.0|\bar{a}.0 \equiv a.\bar{a}.0 + a.a.0 + \tau.0 \). \( P \mid B \) is the process that cannot engage in actions in \( B \) except for synchronisation, e.g., \( (a.0|\bar{a}.0) \mid \{a\} \equiv \tau.0 \), \( (a.0) \mid \{a\} \equiv 0 \). \( \mu X.P \) is the process that executes \( P \) recursively.

Equivalence based on bisimulations is the preferred choice for discriminating among CCS processes. We will use strong simulation to prove the correctness of our translation.

**Definition 3** (Strong Bisimulation \cite{21, 17}). A strong bisimulation is a symmetric binary relation \( \mathcal{R} \) on processes satisfying the following: \( P \mathcal{R} Q \) and \( P \xrightarrow{\alpha} P' \) imply that

\[
\exists Q' : Q \xrightarrow{\alpha}, Q' \wedge P' \mathcal{R} Q'
\]

\( P \) is strong bisimilar to \( Q \), written \( P \sim Q \), if \( P \mathcal{R} Q \) for some strong bisimulation \( \mathcal{R} \).

**CCSTau**. CCSTau \( [4] \) extends CCS with visible synchronisations, viz., the result of synchronisation on a pair \( (a, \bar{a}) \) is the visible action \( \tau[a, \bar{a}] \) instead of the visible action \( \tau \). This makes it easier to guarantee that when two processes synchronise in CCS(Tau), their CSP translation also synchronises. The syntax
of CCSTau processes is defined by the following grammar:

\[ P, Q, R ::= 0 \mid \alpha.P \mid P + Q \mid P \parallel Q \mid P \mid B \mid \mu X.P \mid P_{\gamma}B \mid X \]

\[ \alpha ::= \tau \mid \pi \mid a \]

\[ \beta ::= \alpha \mid \tau[\overline{a} \overline{a}] \]

The parallel operator in CCSTau is denoted \( \parallel \). CCSTau also defines a hiding operator, denoted \( \backslash \), which can hide all actions including \( \tau[\overline{a}, \overline{a}] \) actions. The restriction operator behaves as in CCS, does not apply to \( \tau[\overline{a}, \overline{a}] \) actions. Rules for these operators are given hereafter:

\[
\begin{align*}
\text{Par} : & \quad P \xrightarrow{\beta} P' \quad \xrightarrow{\beta} P', Q \rightarrow P', Q \\
\text{Res} : & \quad P \xrightarrow{\beta} P' \quad \beta = \tau[\overline{a}] \text{ or } \beta \notin B \\
\text{Hide} : & \quad P \xrightarrow{\beta} P' \quad \beta \notin B \\
\text{Com : } & \quad P \xrightarrow{\tau[\overline{a}]} P', Q \xrightarrow{\alpha} Q',
\end{align*}
\]

All other CCS operators are also CCSTau operators.

**CCS-to-CCSTau.** Translation function \( c_{2ccs} \tau \) translates CCS processes into CCSTau, is correct up to strong bisimulation. For any CCS process \( P \) other than CCS-parallel operator, \( c_{2ccs} \tau(P) = P \). For the parallel operator: \[ c_{2ccs} \tau(P|Q) \equiv (c_{2ccs} \tau(P)|c_{2ccs} \tau(Q)) \backslash \{ \tau[\overline{a}] | a \in L(P), \overline{a} \in L(Q) \} \] (c2ccs τ-par-def)

### 2.3 CSP

CSP (Communicating Sequential Processes) \[14, 22\] is a process algebra that allows reasoning about concurrent systems. In CSP, a (concurrent) program is represented as a process, whose behaviour is entirely determined by the possible actions of the program, represented as events. The set of events that a process \( P \) can possibly perform is denoted by \( \mathcal{E}(P) \). Event \( \tau \) denotes invisible actions, hidden from the environment; event \( \checkmark \) denotes successful termination, by opposition say to deadlock and abortion. Both denotational and operational semantics have been defined for CSP processes, in terms of traces. The syntax of some CSP processes is defined by the following BNF:

\[
\begin{align*}
\text{CSP} & ::= \text{SKIP} \mid \text{STOP} \mid \alpha \sim P \mid P \parallel Q \mid P \square Q \mid P \parallel Q \mid P \parallel Q \parallel Q \mid f(P) \mid P \backslash B \mid \mu X.P \\
\alpha & ::= a \mid a?x \mid a!m
\end{align*}
\]

The SOS semantics of CSP processes are given in Table. Informally: \( \text{SKIP} \) is the process that refuses to engage in any event, terminates immediately, and does not diverge. \( \text{STOP} \) is the process that is unable to interact with its environment. \( \alpha \sim P \) is the process that first engages in event \( \alpha \) then behaves like \( P \). \( P \parallel Q \) is the process that behaves like \( P \) or \( Q \), where the choice is decided by the environment.

\[1\text{The set of labels of a CCS process } P, L(P), \text{corresponds to the set of events } \mathcal{E}(Q) \text{ for a CSP process } Q.\]
Table 2: SOS rules for CSP \cite{22}

\begin{align*}
\text{Prefix: } (a \leadsto P) & \xrightarrow{a} P \\
\text{IntChoice: } P_1 \sqcap P_2 & \xrightarrow{\circ} P_1 \\
\text{ExtChoice: } & \frac{P_1 \xrightarrow{a} P'}{P_1 \sqcap P_2 \xrightarrow{a} P'} \\
\text{FacePar: } & \frac{P_1 \xrightarrow{a} P'}{P_1 \parallel P_2 \xrightarrow{a} P' \parallel P_2} \\
\text{Hide: } & \frac{P \xrightarrow{a} P'}{P \parallel B \xrightarrow{a} P' \parallel B} \\
\text{FwdRen: } & \frac{f(P) \xrightarrow{f(a)}}{f(P')} \\
\text{Rec: } & \frac{P \xrightarrow{N = P}}{N \xrightarrow{P'}} \\
\text{Skip: } & \xrightarrow{\text{STOP}} \\
\end{align*}

$P \parallel Q$ behaves like the parallel execution of $P$ and $Q$ where the latter must both synchronise on the set of events $B$. When $B = \{\}$, we say that $P$ and $Q$ interleave, denoted by $P \parallel Q$; if $B = \mathcal{A}(P) \cap \mathcal{A}(Q)$ we also write $P \parallel Q$. $f(P)$ engages in $f(a)$ whenever $P$ engages in $a$. $P \parallel B$ is the process that engages in all events of $P$ except those in $B$. $\mu X. P$ is the process that executes $P$ recursively.

Equivalence based on (enriched versions of) traces is the preferred choice for distinguishing CSP processes. We kindly refer the reader to \cite{14,22} for details.

### 2.4 CCS-to-CSP Translation

**Notation.** Given two functions, say $f_1$ and $f_2$, $f_1 \circ f_2$ denotes functional composition, viz., $f_1(f_2)$.

In this section, we present $ccs2csp$ \cite{4}, the translation from CCS-to-CSP, correct up to strong bisimulation.

**Definition 4** ($ccs2csp$ \cite{4}). Let $P$ be a CCS process. Then:

\begin{align*}
ccs2csp(P) & \equiv \alpha 2\alpha \circ (t2csp \circ c2ccst(P)) \cap_{csp} \{a_{ij} | a_{ij} \in \mathcal{A}(t2csp(c2ccst(P)))\} \\
t2csp(P) & \equiv (t \circ \text{comm} \circ g^* \circ \text{ix}(P)) \cap_{csp} \{\text{tau}\} \\
g^* & \equiv \{\tau \mapsto \tau, a_i \mapsto \{a_i\} \cup \{a_{ij} | a_{ij} \in S, i < j\} \cup \{a_{ij} | a_{ij} \in S, j < i\}\} \\
\text{comm} & \equiv \{\tau \mapsto \tau, a_i \mapsto \bar{a}_i, a_{ij} \mapsto a_{ij}, a_{ij} \mapsto a_{ij}\} \\
\alpha 2\alpha & \equiv \{a_i \mapsto a\}
\end{align*}

where $\text{ix}$ generates unique indexed prefixes such that a name $b$ maps to a set of indexed names $b_i, i \geq 1$; $g^*$ generates unique double-indexed names for every pair of synchronising names; $\text{comm}$ renames every
synchronising coname into the corresponding name (so they can synchronise in CSP); and \( t \) \( l \) translates CCS operators into corresponding CSP operators. We kindly refer the reader to [4] for details.

**Example 1 ([4]).** The translation of CCS binary synchronisation into CSP can be illustrated succinctly as follows:

\[
\begin{align*}
\text{ccs2csp}(a.0|\bar{a}.0) & \quad \text{(ccs2csp-def)} \\
= & ai2a \circ t2csp(c2ccs\tau(a.0|\bar{a}.0))_{\text{vsp}} \{a_{ij}\} \quad \text{(c2ccs\tau-par-def)} \\
= & ai2a \circ t2csp((a.0|\bar{a}.0)_{\exp{v}} \{\tau[a|\bar{a}]\})_{\text{vsp}} \{a_{ij}\} \\
= & ai2a \circ t \circ \text{comm} \circ g^* (\{\}, ix((a.0|\bar{a}.0)_{\exp{v}} \{\tau[a|\bar{a}]\})_{\text{vsp}} \{\tau\} \{a_{ij}\}) \quad \text{(ix-def)} \\
= & ai2a \circ t \circ \text{comm} \circ g^* ((a_{1.0}|_{\exp{v}} \bar{a}_{2.0}).)_{\text{vsp}} \{\tau\} \{a_{ij}\} \\
= & ai2a \circ t \circ \text{comm} ((a_{1.0} + a_{12.0})|_{\exp{v}} (\bar{a}_{2.0} + \bar{a}_{12.0}).)_{\text{vsp}} \{\tau\} \{a_{12}\} \\
= & ai2a \circ (a_1 \boxdot a_{12} \leadsto \text{STOP}) \quad \text{||} \quad (a_2 \boxdot a_{12} \leadsto \text{STOP}) \quad \text{vsp} \{\tau\} \{a_{12}\} \\
= & (a \boxdot a_{12} \leadsto \text{STOP}) \quad \text{||} \quad (a \boxdot a_{12} \leadsto \text{STOP}) \quad \text{vsp} \{\tau\} \{a_{12}\}
\end{align*}
\]

In CCS, a name can be used both for interleaving and for synchronisation. This is reflected in the translation above by generating indexed names \( a_i \) and \( \bar{a}_2 \) for interleaving; then for the synchronisation pair \( (a_1, \bar{a}_2) \), a unique synchronisation name \( a_{12} \) is generated. More generally, there will be as many \( a_{ij} \) synchronisation names as there are of synchronisation on name \( a \).

In the next section, we extend CSP with m-among-n synchronisation, then derive 2-among-n (binary) synchronisation. In the end, we will be able to translate CCS binary synchronisation into CSP binary synchronisation.

## 3 CSP plus m-among-n Synchronisation

Multiway synchronisation in CSP is maximal, viz., all processes that can synchronise must synchronise. This is also called the maximal (or n-ary) coordination paradigm ([9]): if \( n \) processes are ready to synchronise on event \( a \), then all \( n \) processes must synchronise together. Can we generalise this to allow only m-among-n (\( 2 \leq m \leq n \)) processes to synchronise instead? If the answer is yes then binary synchronisation can be defined as 2-among-n coordination and n-ary synchronisation as n-among-n coordination. Garavel and Sighireanu [9] define \( m/n \) coordination for the language E-LOTOS.

First, let us generalise CSP (n-ary) interface parallel operator ([22]).

\[
\text{IndxlfacePar} : \begin{array}{l}
P_j \xrightarrow{a \in B^r} P'_j \quad [a \notin B^r, k \neq j] \\
\left\| \begin{array}{l}
P_i \xrightarrow{a \in B^r} P'_i \\
B \end{array} \right\| \quad \text{for} \quad P_i \xrightarrow{a \in B^r} P'_i \\
\end{array}
\]

**Definition 5 (a#m clause [9]).** Let \( I = \{1, \ldots, n\}, n \in \mathbb{N}, n \geq 2 \). Let \( m \) be a natural number in the range \( 2, \ldots, n \) associated to an \( a \)-event such that a clause \( a \# m \) denotes that \( m \) processes are allowed to synchronise on event \( a \) at once. Each clause \#m is optional: if omitted, \( m \) has default value \( n \).
The rules for \( m/n \) indexed interface parallel composition are given hereafter.

\[
M/N-\text{IndexFacePar} : \quad P_j \xrightarrow{a} P_j' \quad [a \# m \notin B^\vee \times \{2, \ldots, n\}, k \neq j] \\
\quad \begin{array}{c}
 B \times \{2, \ldots, n\} \\
 B \times \{2, \ldots, n\}
\end{array}
\]

\[
P_1 \xrightarrow{a} P_1' \ldots P_n \xrightarrow{a} P_n' \quad [a \# m \in B^\vee \times \{2, \ldots, n\}, j \in J, k \neq j] \\
\quad \begin{array}{c}
 B \times \{2, \ldots, n\} \\
 B \times \{2, \ldots, n\}
\end{array}
\]

We can then derive binary-only synchronisation by imposing that every event in set \( B \) allows 2(only)-among-n processes to synchronise.

\[
2/N-\text{IndexFacePar} : \quad P_1 \xrightarrow{a} P_1' \ldots P_n \xrightarrow{a} P_n' \quad [a \# 2 \in A^\vee \times \{2\}, j \in J, k \neq j] \\
\quad \begin{array}{c}
 B \times \{2\} \\
 B \times \{2\}
\end{array}
\]

Similarly, we derive \( n \)-ary-only synchronisation by imposing that every event in set \( B \) allows \( n \)-among-n processes to synchronise. We easily verify that rules \( N/N-\text{IndexFacePar} \) and \( \text{IndexFacePar} \) (synchronisation) are the same.

\[
N/N-\text{IndexFacePar} : \quad P_1 \xrightarrow{a} P_1' \ldots P_n \xrightarrow{a} P_n' \quad [a \# n \in B^\vee \times \{n\}] \\
\quad \begin{array}{c}
 B \times \{n\} \\
 B \times \{n\}
\end{array}
\]

**Correctness of \( M/N-\text{IndexFacePar} \) rule.** Let us call CSPmn the extension of CSP with \( m \)-among-n synchronisation. We argue here that CSPmn is a conservative extension of CSP, i.e., CSPmn preserves the axioms of CSP.

The proof method is suggested to us by function \( g^* \) [4]. For binary synchronisation, select process pairs that must synchronise and assign them a unique synchronisation index. E.g.,

\[
a \parallel a \parallel a \quad \text{maps to} \quad (a_{12} \Box a_{13}) \parallel (a_{12} \Box a_{23}) \parallel (a_{13} \Box a_{23})
\]

Then, for \( m \) processes to synchronise among \( n \), generate a unique index for all possible combinations of \( m \) processes among \( n \), e.g.,

\[
a \parallel a \parallel a \quad \text{maps to} \quad (a_{12} \Box a_{13} \Box a_{14}) \parallel (a_{12} \Box a_{23} \Box a_{24}) \parallel (a_{13} \Box a_{23} \Box a_{34}) \parallel (a_{14} \Box a_{24} \Box a_{34})
\]

\[
a \parallel a \parallel a \quad \text{maps to} \quad (a_{123} \Box a_{124} \Box a_{134}) \parallel (a_{123} \Box a_{124} \Box a_{234}) \parallel (a_{123} \Box a_{134} \Box a_{234}) \parallel (a_{124} \Box a_{134} \Box a_{234})
\]

\[
a \parallel a \parallel a \quad \text{maps to} \quad (a_{1234}) \parallel (a_{1234}) \parallel (a_{1234}) \parallel (a_{1234})
\]

\(^2\)The rules in [9] use a different rule format than CSP rules: they use predicates.
From what precedes, there exists a relational renaming, say $G$, such that

$$P_j \sim_{a\text{hm},j} P_j[G(a)/a]$$

We can thus define (CSPmn parallel operator) $\parallel$ in terms of both (CSP parallel operator) $\parallel$ and (CSP relational renaming) $G(a)$. Therefore, CSPmn is a conservative extension of CSP, viz., preserves CSP axioms (cf. Appendix A for a full proof).

4 CCSTau Transformations

![Figure 1: CCS-to-CSPmn Translation workflow](image)

The different stages of our translation are shown in Fig. 1.

**Pairwise vs. Multiway Synchronisation** Recall, a CCSTau name has both interleaving and synchronisation semantics. We hence have to generate two distinct CSP events for a single CCS name. Also, it is possible to hide $\tau[a|\bar{a}]$ synchronisation actions in CCSTau (typically, to obtain a CCS process—cf. Def[2ces\tau-par-def]). Then, it will be convenient to ignore them. Let $g^2$ define the function that generates a synchronisation name for any CCS name.

**Definition 6** ($g^2(\alpha)$).

$$g^2(S, \tau) \equiv \tau$$
$$g^2(S, \tau[a|\bar{a}]) \equiv \{\tau[a, \bar{a}]\}$$
$$g^2(S, a) \equiv \{a\} \cup \{a_S|\bar{a} \in S\}$$
$$g^2(S, B) \equiv \{g^2(S, a) | a \in B, \bar{a} \in S\}$$

Given a set of names generated by $g^2$, $a$-names denote interleaving, whilst $a_S$-names denote synchronisation. The application of $g^2$ to processes is given hereafter.

**Definition 7** ($g^2(P)$). Let $P$ be a CCS process. Let $g^2(P) \equiv g^2(\{\}, P)$.

$$g^2(S, 0) \equiv 0$$
$$g^2(S, \alpha.P) \equiv \sum_{b \in g^2(S, \alpha)} b.g^2(S, P)$$
$$g^2(S, P + Q) \equiv g^2(S, P) + g^2(S, Q)$$
$$g^2(S, P|Q) \equiv g^2(S \cup \mathcal{A}(Q), P) \parallel g^2(S \cup \mathcal{A}(P), Q)$$
$$g^2(S, P \mid B) \equiv g^2(S, P) \mid g^2(S, B)$$
$$g^2(S, P \parallel B) \equiv g^2(S, P) \parallel g^2(S \cup B, B)$$
$$g^2(S, \mu X.P) \equiv \mu X.g^2(S, P)$$
$$g^2(S, X) \equiv X$$

Note the difference between restriction and hiding. Names $g^2(S, B)$ are generated between a process and its environment. Only those names will be restricted, understood that (restricted) $B$ names cannot interact with their environment. Internal synchronisation on $B$ names, however, will not be restricted (until later in CSP). In contrast, for hiding, internal synchronisation on $B$ must be hidden as well, hence we hide names $g^2(S \cup B, B)$ instead.
Example 2. Let us illustrate the translation of restriction.

\[ g^2(\{\}, (a.0) \| \bar{a}.0) \uparrow \{a\} ) = (g^2(\{\}, (a.0) \| \bar{a}.0) \uparrow g^2(\{\}, \{a\}) ) \uparrow \{a\} \]  
\[ = (g^2(\{\}, (a.0) \| \bar{a}.0) \uparrow g^2(\{\}, \{a\}) ) \uparrow \{a\} \]
\[ (a.0 + \bar{a}.0) \| (a.0 + \bar{a}.0) \uparrow \{a\} \]

Contrast with hiding, which hides both \( a \) and \( a_s \). (Recall \( \bar{\nu}(a) = \bar{\nu}(a, \bar{a}) \).

\[ g^2(\{\}, (a.0) \| \bar{a}.0) \backslash \{a\} \]  
\[ = g^2(\{\}, (a.0) \| \bar{a}.0) \backslash \{a, \bar{a}\} \]  
\[ = g^2(\{\}, (a.0) \| \bar{a}.0) \backslash g^2(\{a, \bar{a}\}, \{a, \bar{a}\}) \]  
\[ = (g^2(\{a, \bar{a}\}, \{a, \bar{a}\}) \backslash g^2(\{a, \bar{a}\}, \{a, \bar{a}\}) \backslash \{a, \bar{a}, a_s, \bar{a}_s\} \]  
\[ = ((a.0 + a_s.0) \| (a.0 + \bar{a}_s.0)) \backslash \{a, a_s\} \]

Finally, consider hiding the synchronisation action \( \tau [a|\bar{a}] \), this turns out to be vacuous.

\[ g^2(\{\}, (a.0) \| \bar{a}.0) \backslash \{\tau[a|\bar{a}]\} \]  
\[ = g^2(\{\}, (a.0) \| \bar{a}.0) \backslash g^2(\{a, \bar{a}\}, \{a, \bar{a}\}) \]  
\[ = (g^2(\{a, \bar{a}\}, \{a, \bar{a}\}) \backslash g^2(\{a, \bar{a}\}, \{a, \bar{a}\}) \backslash \tau[a|\bar{a}] \]  
\[ = ((a.0 + a_s.0) \| (a.0 + \bar{a}_s.0)) \backslash \tau[a|\bar{a}] \]

Parallel Composition. In CSP, synchronisation pairs \((a_s, \bar{a}_s)\) will not be able to synchronise. We hence update the rename function to translate names into names.

Definition 8 (comm). \( \text{comm} \equiv \{\tau \mapsto \tau, a \mapsto a, \bar{a} \mapsto \bar{a}, a_s \mapsto a_s, \bar{a}_s \mapsto \bar{a}_s\} \).

Link CCSTau-to-CSPmn In [4], function \( tl \) translates CCSTau operators into CSP operators, without consideration for differences in their respective alphabets. Hereafter, we define \( tl_3 \), to map CCS binary synchronisation into CSPmn binary synchronisation. All other operators are translated as before, viz., \( tl_3(P) = tl(P) \) for all process expressions other than parallel composition. Additionally, because of the possibility to hide \( \tau [a, \bar{a}] \) synchronisation actions in CCSTau, we translate CCSTau hiding operator also, translation which was not needed for \( tl \).

Definition 9 (tl3). Let \( \tau \) be a CSP event that cannot synchronise.

\[ tl_3(0) \equiv \text{STOP} \]
\[ tl_3(\tau.P) \equiv \tau \text{\_to\_} tl_3(P) \]
\[ tl_3(a.P) \equiv a \text{\_to\_} tl_3(P) \]
\[ tl_3(P \parallel B) \equiv tl_3(P) \uparrow_{\text{csp}} B \]
\[ tl_3(P \downarrow B) \equiv tl_3(P) \downarrow_{\text{csp}} B \]
\[ tl_3(\mu X.P) \equiv \mu X.tl_3(P) \]
\[ tl_3(X) \equiv X \]

Note that \( tl_3(P \downarrow \{\tau[a|\bar{a}]\}) = tl_3(P) \downarrow \{\tau[a|\bar{a}]\} = tl_3(P) \), since \( \tau[a|\bar{a}] \) actions do not occur in the translated term, \( tl_3(P) \). This is necessary, as illustrated subsequently.
Example 3. CCS process $a | \bar{a} | a$, by $c2ccst$, corresponds to CCSTau process

$$((a | \bar{a}) | x \tau \{a | \bar{a}\} | x a) | \tau \{a, \bar{a}\}$$

By $g^2$, this becomes process

$$(((a + a_S) | x \tau \{a | \bar{a}\} | x (a + a_S)) | \tau \{a | \bar{a}\})$$

Then, by $t_3$, it becomes

$$((a \square a_S) \parallel (\bar{a} \square \bar{a}_S)) \parallel_{cs p} \{a | \bar{a}\} \parallel_{cs p} (a \square a_S)$$

Thanks to $\parallel_{cs p} \{a | \bar{a}\}$ being vacuous, there will be two possible synchronisations on $a_S$, corresponding to the original CCS behaviour.

The following abbreviation translates CCSTau into CSPmn.

Definition 10 (CCSTau to CSPmn). Let $P$ be a CCSTau process. Then:

$$t2csp_3(P) \triangleq (t_3 \circ \text{comm} \circ g^2(P)) \parallel_{cs p} \{\tau\}$$

Link CCS-to-CSPmn. We obtain the translation from CCS to CSP by translating CCS into CCSTau first, using $c2ccst$ (Def $c2ccst-par-def$), then translating CCSTau into CSPmn, using $t2csp_3$ (Def $10$), and finally hiding every $a_S$ synchronisation event.

Definition 11 (CCS to CSPmn). Let $P$ denote a CCS process. Then:

$$ccs2csp_3(P) \triangleq (t2csp_3 \circ c2ccst(P)) \parallel_{cs p} \{a_S | aS \in A (t2csp_3 \circ c2ccst(P))\}$$

Example 4. The translation of CCS binary synchronisation into CSPmn can be illustrated succinctly as follows:

$$ccs2csp_3(a.0 | \bar{a}.0)$$

$$= (t2csp_3 \circ c2ccst(a.0 | \bar{a}.0)) \parallel_{cs p} \{aS | \ldots\}$$

$$= t2csp_3((a.0 | x \bar{a}.0) | \tau \{a | \bar{a}\}) \parallel_{cs p} \{aS\}$$

$$= t_3 \circ \text{comm} \circ g^2(\{, (a.0 | x \bar{a}.0) | x \tau \{a | \bar{a}\} | \tau \{\tau\} | \parallel_{cs p} \{aS\})$$

$$= t_3 \circ \text{comm}((a.0 | x aS.0) | x (\bar{a}.0 + \bar{a}_S.0)) | \tau \{a | \bar{a}\} \parallel_{cs p} \{aS\}$$

$$= t_3((a.0 | x aS.0) | x \tau \{a | \bar{a}\}) \parallel_{cs p} \{\tau\} \parallel_{cs p} \{aS\}$$

$$= (a \square a_S \sim \text{STOP} \parallel_{\{aS \#2\}} (\bar{a} \square a_S \sim \text{STOP})) \parallel_{cs p} \{\tau, aS\}$$

Example 5. The translation of recursion with nested parallel can be illustrated as follows.

Let $P \triangleq \mu X. (a | \bar{a}.X)$ (or equiv. $P \triangleq a.0 | \bar{a}.P$) be a CCS process. Then, $ix(P) = a_1 | a_2.\langle_{ix(3\ldots)}(P)$, where $ix(3\ldots)$ denotes that indexing excludes indices 1 and 2. Let us unfold $P$ one step, then:

$$\begin{align*}
P &= a | \bar{a}.(a | \bar{a}.P) \\
ix(P) &= a_1 | a_2.\langle_{a_3 | a_4.\langle_{ix(5\ldots)}(P)}
\end{align*}$$
The synchronisation pairs are thus \((a_1, \bar{a}_2), (a_1, \bar{a}_3), \ldots\), that is, the set \(\{(a_1, \bar{a}_k) | k \geq 1\}\). Then:

\[
g^*(P) = (a_1 + \sum_{k \geq 1} a_{12k}) | (\bar{a}_2 + \bar{a}_12) . g^*(P)
\]

We will not be able to generate all the \(a_{12k}\) indices since recursion is unbounded. For closure, we give the tentative translation of \(P\) with \(ccs2csp:\)

\[
ccs2csp(P) = \left( (a \sqcap \sqcup a_{12k})_{k \geq 1} \parallel (\bar{a}_2 \sqcap \bar{a}_12) \leadsto a12a \circ t2csp \circ c2cst\tau(P) \right) \psi_{\pi}(a_i\ldots)
\]

In contrast, let us define \(ccs2csp_3(P)\). Then:

\[
g^2(P) = (a + a_S) | (\bar{a} + \bar{a}_S) . g^2(P)
= (a + a_S) | (\bar{a} + \bar{a}_S) . ((a + a_S) | (\bar{a} + \bar{a}_S) . g^2(P))
\]

We can unfold \(P\) multiple times, we only ever generate a single name for synchronisation. Then:

\[
ccs2csp_3(P) = \left( (a \sqcap \sqcup a_S)_{a_S\#2} \parallel (\bar{a} \sqcap \bar{a}_S) \leadsto t2csp_3 \circ c2cst\tau(P) \right) \psi_{\pi}(a_S)
\]

5 Gstar Implements 2/n-Synchronisation

We discuss here the relation between \(g^*\)-renaming (§4) and m-among-n synchronisation (§3) approaches.

Recall, function \(g^*\) (Def.4, [4]) computes for a CCSTau process \(P\) all the substitute names corresponding to distinct synchronisation possibilities of \(P\) with its environment, plus interleaving. We have proposed an alternative solution based on extending CSP with 2-among-n synchronisation, derived from first extending CSP with m-among-n synchronisation. Whilst this second solution is more elegant than the gstar-renaming one, the problem of its immediate implementability in a tool like FDR has been raised.

Given the current version of FDR, m-among-n synchronisation cannot be implemented directly. We remark, however, that one effect of m-among-n synchronisation is to select, using non-deterministic choice, the \(m\) processes that are allowed to synchronise; effect which is precisely what function \(g^*\) achieves through renaming. We discuss how to relate both results.

Let us refer by CSPgstar the CSP process expressions resulting from translation \(ccs2csp\). We can translate CSPgstar expressions into CSPmn expressions as follows.

**Definition 12 (gstar2m/n).** Let \(a_{ij}\) be an \(g^*\) name, \(a_S\) an \(g^2\) name. Then: \(g^*2g^2 \equiv \{\tau \mapsto \tau, a_{ij} \mapsto a_S\}\)

While \(g^*2g^2\) is a simple renaming function, its application to CSP processes is modified specifically for the parallel operator such as to map \(\parallel\) unto \(\parallel\) (instead of \(\parallel\)).

**Definition 13.** Let \(P\) be a CSP process.

\[
g^*2g^2(\text{STOP}) \equiv \text{STOP} \quad g^*2g^2(P \parallel Q) \equiv g^*2g^2(P) \parallel g^*2g^2(Q)\]
\[
g^*2g^2(\alpha \leadsto P) \equiv g^*2g^2(\alpha) \leadsto g^*2g^2(P)\quad g^*2g^2(P_{\neg m}B) \equiv g^*2g^2(P)_{\psi_{\pi}}g^*2g^2(B)\]
\[
g^*2g^2(P \sqcap Q) \equiv g^*2g^2(P) \sqcap g^*2g^2(Q)\quad g^*2g^2(P \sqcup Q) \equiv g^*2g^2(P) \sqcup g^*2g^2(Q)
\]

\(^3\)We are lucky that we can tell in advance what the synchronisation indices are, because process \(P\) is a simple case.
Theorem 1. Let $P$ be a CCS processes. Then: $g^*2g^2 \circ \text{ccs2csp}(P) = \text{ccs2csp}_3(P)$.

Proof. By induction on the structure of CCS processes. When $P$ does not mention CCS parallel, the proof is straightforward. We develop the proof for the parallel case only. We have:

\[ g^*2g^2 \circ \text{ccs2csp}(P | Q) = g^*2g^2 \circ (t2\text{csp}(P) | \{\text{tau}, a_{ij}\}) \]

\[ = g^*2g^2 \circ (ai2a \circ t2\text{csp}(P) \setminus \{a_{ij}\} | \{\text{tau}\}) \]

\[ = g^*2g^2 \circ \text{ccs2csp}(P) \setminus \{a_{ij}\} | \{\text{tau}\}) \]

\[ = \text{ccs2csp}_3(P | Q) \]

We say that $g^*$ implements 2-among-n synchronisation.

6 Conclusion and Future Work

[4] proposes a translation of CCS into CSP based on the $g^*$-renaming approach whereby if two processes can synchronise on an action $b$, then a name unique to these two processes, say $b_{ij}$, is generated to substitute $b$. Thus, if more than two processes could initially synchronise on $b$, only two processes will ever be able to synchronise on $b_{ij}$ after application of $g^*$.

In this paper, we propose an alternative, the m-among-n synchronisation approach, whereby we first extend CSP multiway synchronisation (or n-among-n) to m-among-n synchronisation (extension called CSPmn), from which we derive 2-among-n or binary synchronisation for CSP processes. We then translate CCS binary synchronisation into CSPmn binary synchronisation. Unlike the $g^*$-renaming approach, the m/n-approach is not limited by parallel under recursion since we can generate a single synchronisation name, say $a_S$, independently of the number of processes meant to synchronise on $a_S$.

We have also shown that CSPmn is a conservative extension of CSP (viz., preserves CSP axioms) by defining (CSPmn) m-among-n synchronisation in terms of both (CSP) multiway (or n-among-n) synchronisation and relational renaming.

We are tempted to affirm that m-among-n synchronisation is more expressive than both 2-among-n and n-among-n synchronisation. However, Hatzel et al. [11] propose an encoding from CSP into CCS whereby they encode CSP multiway synchronisation based on CCS binary synchronisation. Our work suggests that in trying to translate CSP into CCS, it would be easier to extend CCS with multiway synchronisation, as we have done here for CSP. Other works on the translation from CSP into CCS include [2], [3], [12], and [10].

We have proposed here the translation from CCS to CSP only. The main reason for this is our interest in using CSP tools such as FDR for reasoning about CCS processes. With regard to this concern, the $g^*$-renaming approach is more readily implementable than the m/n-approach. The latter would require extending FDR with semantics (viz. rules) for m-among-n synchronisation. Alternatively, m-among-n synchronisation can be implemented using function $g^*_n$ (Def.15), however, with the limitation on parallel under recursion similar to $g^*$ (cf. [4]). Mechanising our results in Isabelle theorem prover is also to be explored in the future.
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A Proof that CSPmn is a Conservative Extension

In order to prove that CSPmn is conservative, we need to define some auxiliary functions. First, we uniquely index the prefixes of CSP processes.

Property 1. Let $P$ be a CSP process.

\[
\begin{align*}
ix(STOP) &= STOP \\
ix(a \rightarrow P) &= a_i \rightarrow ix_{i-1}(P) \\
ix(P \sqcap Q) &= ix_1(P) \sqcap ix_2(Q) \\
ix(P \sqcup Q) &= ix_1(P) \sqcup ix_2(Q)
\end{align*}
\]

\[
ix(P \parallel Q) = ix_1(P) \parallel ix_2(Q)
\]

\[
B \triangleq \{ a_i \# m | a_i \in \mathcal{A}(ix_1(P)) \cup \mathcal{A}(ix_2(Q)) \}
\]

\[
ix(P_{\setminus\{a\}}) = ix(P)_{\setminus\{a_i|a_i \in \mathcal{A}(ix(P))\}}
\]

\[
ix(\mu X . P) = \mu X . ix(P)
\]

\[
ix(X) = X
\]

where $ix_{\cdot i}$ is some indexing scheme which does not assign the index, and $ix_1, ix_2$ are indexing schemes that assign disjoint indices.

Then, using $ix$-generated indices we generate unique synchronisation indices. Given a set $\{ a_i \}$ of parallel prefixes and a number $m$ of processes meant to synchronise together, $g_{a_i \# m}^*$ generates a unique synchronisation index $a_{i_1\ldots i_m}$.

Definition 14. Let $S, B$ denote sets of indexed events.

\[
g_{a_i \# m}^*(S, a_i) \triangleq \{ a_i_{i_1\ldots i_m} | i_1 < \ldots < i_m, \{a_{i_k} | 1 < k \leq m \} \subseteq S \} \cup \{ a_{i_{la \ldots i_m}} \} \cup \{ a_i \mid 1 < k \leq m \} \subseteq S \}
\]

\[
g_{a_i \# m \mid k \in \mathbb{N}}(S, a_i) \triangleq \begin{cases} a_i & a_i \notin \{a_k | k \in \mathbb{N} \} \\ g_{a_i \# m}^*(S, a_i) & \text{otherwise} \end{cases}
\]

Although $g_{a \# m}^*$ denotes relational renaming, we overload its application to processes such that it translates $\parallel$ into $\parallel$. This corresponds to the following.

Definition 15. Let $P$ be an $ix$-indexed CSP processes. Let $S$ be a set of $ix$-indexed events. Let $a \# m$ denote the set $\{ a_k \# m_k | k \in \mathbb{N} \}$, $b \# n$ the set $\{ b_j \# n_j | j \in \mathbb{N} \}$. Let $g_{a \# m}^*(P) \triangleq g_{a \# m}^*(\{\}, P)$.

\[
g_{a \# m}^*(S, STOP) \triangleq STOP \\
g_{a \# m}^*(S, a \rightarrow P) \triangleq \sum_{b \in g_{a \# m}^*(a)} b \rightarrow g_{a \# m}^*(S, P) \\
g_{a \# m}^*(S, P \sqcap Q) \triangleq g_{a \# m}^*(S, P) \sqcap g_{a \# m}^*(S, Q) \\
g_{a \# m}^*(S, \mu X . P) \triangleq \mu X . g_{a \# m}^*(S, P) \\
g_{a \# m}^*(S, P_{\setminus\{a\}}) \triangleq g_{a \# m}^*(S, P)_{\setminus\{a\}} \\
g_{a \# m}^*(S, P \parallel Q) \triangleq g_{a \# m \sqcup b \# n}^*(S \cup \mathcal{A}(Q), P) \parallel g_{a \# m \sqcup b \# n}^*(S \cup \mathcal{A}(P), Q)
\]

\[
B \triangleq \bigcup \{ g_{a \# m \sqcup b \# n}^*(S \cup \mathcal{A}(Q), b_j) | b_j \in \mathcal{A}(P) \} \cup \bigcup \{ g_{a \# m \sqcup b \# n}^*(S \cup \mathcal{A}(P), b_j) | b_j \in \mathcal{A}(Q) \}
\]

When $a \# m$ denotes the empty set, we write $g_a^*$ for the corresponding function $g_{a \# m}^*$. Then, the translation of CSPmn into CSP is given by the following.
Definition 16. Let $P$ be a CSP$_{mn}$ process. $mn2csp(P) \supseteq g^* \circ ix(P)$

The following theorem establishes a labelled operational correspondence (Def. 2), which turns out a strong bisimulation (Def. 3), between CSP$_{mn}$ and CSP.

Theorem 2. Let $P$ be a CSP$_{mn}$ process. Let $I$ denote a given sequence of natural numbers.

1. If $P \xrightarrow{a} P'$ then $\exists I : mn2csp(P) \xrightarrow{a_i} Q$ and $Q \equiv mn2csp(P')$
2. If $mn2csp(P) \xrightarrow{a_i} Q$ then $\exists ! P' : P \xrightarrow{a} P'$ and $Q \equiv mn2csp(P')$

Proof. When $P$ does not mention $\parallel$, $mn2csp$ behaves like the identity function, hence the theorem holds. By induction, we prove the case for parallel.

(Thm 2.1) (Induction step: Parallel.) Let $P_1 \xrightarrow{a} P_1'$. Let $P_2, \ldots, P_n$ denote processes such that $m-1$ among them can perform an $a$-transition. For ease, we select one such combinations, $P_2 \ldots P_m$. The following result applies for all possible combinations. —(Hyp-combine)— Then, by M/N-IndxFacePar rule (§3),

$$P_1 \parallel \ldots \parallel P_n \xrightarrow{a_i} P_1' \parallel P_2' \ldots \parallel P_m' \parallel P_{m+1} \parallel \ldots \parallel P_n$$

Assume for each $P_i$ that every occurrence of $a$ in $P_i$ is indexed into $a_i$. (The following applies even if we separate $i$ into distinct indices, e.g., $i_1, i_2, \ldots$, as many as there are of instances of $a$ in $P_i$.) —(Hyp-indx)— Then, by (Hyp-combine), (Hyp-indx), and Def $\exists mn2csp(P_1 \parallel \ldots \parallel P_n) = P_1[a_{12..m}/a] \parallel \ldots \parallel P_m[a_{12..m}/a] \parallel P_{m+1} \parallel \ldots \parallel P_n$

By IndxFacePar rule (§3) and definition of renaming (Tab 2):

$$P_1[a_{12..m}/a] \parallel \ldots \parallel P_m[a_{12..m}/a] \parallel P_{m+1} \parallel \ldots \parallel P_n \xrightarrow{a_{12..m}}$$

Then, by induction hypothesis.

(Thm 2.2) (Induction step: Parallel.) Let $mn2csp(P) \xrightarrow{a_i} Q$. By Par rule, $mn2csp(P) \parallel mn2csp(P_2) \xrightarrow{a_i} Q \parallel mn2csp(P_2)$, $a_i \notin \mathcal{A}(mn2csp(P_2))$. By induction hypothesis, $\exists ! P' : P \xrightarrow{a_i} P'$ and $Q \equiv mn2csp(P')$. Then, by Par rule, $P \parallel P_2 \xrightarrow{a_i} P' \parallel P_2$. Moreover, $Q \parallel mn2csp(P_2) \equiv mn2csp(P') \parallel mn2csp(P_2) = mn2csp(P') \parallel P_2$, by Def $\exists$\)

As a consequence, when $m$-among-$n$ CSP$_{mn}$ processes, $\parallel P_j$, will synchronise on $a$, $m$-among-$n$ CSP processes, $\parallel P_j[a_{12..m}/a]$, will synchronise on $a_{12..m}$, where $12..m$ denotes any combination of $m$ potential synchronising processes. We say that $mn2csp$ implements $m$-among-$n$ synchronisation.